

Integrating Crew Scheduling and Crew Rostering for rail freight with train delays

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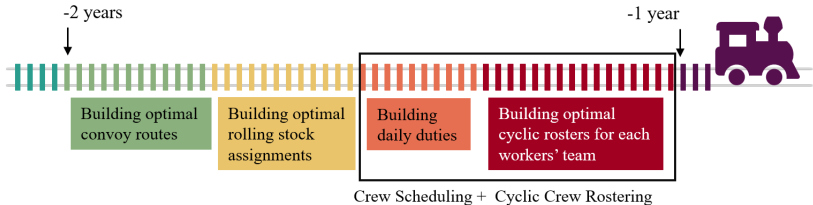
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Rail freight in France

- Modal share for rail freight: 18% in Europe (10% in France)
- Between 1800 and 2000 trains per week
- Many differences with passengers transportation:
 - Priority goes to passengers
 - Trains mostly at night

Resource planning



Contributions

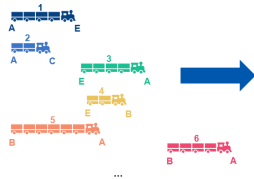
We propose a complete methodology:

- modeling the “resilience” of rosters to train delays at the SNCF
- solving the integrated problem while handling train delays without sampling
- providing a tight lower bound
- leading to an average 8% cost reduction for the deterministic version

Problem definition

Input: Trains on a typical week

Output: Covering of trains by “blocks” with minimum cost, each block assigned to a team (each block then placed in a cyclic roster)



Team A:

| sun | mon | tue |
|---------|---------|---------|
| duty 7 | duty 1 | on-call |
| 10h-17h | 12h-21h | |
| A - A | A - A | |

| sat | sun | mon | tue |
|---------|--------|---------|--------|
| duty 5 | duty 6 | duty 2 | duty 3 |
| 11h-17h | 5h-16h | 12h-19h | 5h-11h |
| A - E | E - A | A - B | B - A |

Team B:

| mon | tue | wed |
|---------|---------|--------|
| duty 4 | duty 8 | duty 9 |
| 12h-20h | 11h-17h | 5h-12h |
| B - B | B - B | E - B |

cost = 10

Team A:

| mon | tue | wed | thu | fri | sat | sun |
|---------|---------|-----|-----|-----|---------|---------|
| duty 1 | on-call | R | R | R | duty 5 | duty 6 |
| 12h-21h | | | | | 11h-17h | 5h-16h |
| A - A | | | | | A - E | E - A |
| duty 2 | duty 3 | R | R | R | | duty 7 |
| 12h-19h | 5h-11h | | | | | 10h-17h |
| A - B | B - A | | | | | A - A |

Team B:

| mon | tue | wed | thu | fri | sat | sun |
|---------|---------|--------|-----|-----|-----|-----|
| duty 4 | duty 8 | duty 9 | | | | |
| 12h-20h | 11h-17h | 5h-12h | R | R | R | R |
| B - B | B - B | E - B | | | | |

Stochastic train delays: context

Train departure and arrival delays (**primary delays** and **secondary delays**) → disruptions of rosters with propagation within duties.

When delays exceed some threshold, disruptions occur and they induce prohibitive adjustments:

- a full duty, or some of its trains, must be operated by backup drivers;
- an on-call must be added within a block or at its end.

Stochastic train delays: fragility and assumptions

Assumptions:

- primary delays are independent variables (not necessarily identically distributed),
- their distributions are known,
- their support is finite.

H : random variable for arrival times (with primary and secondary delays)

$\sigma(h, b)$: number of disruptions in the realization $H = h$.

Roster “fragility” score:

$$\text{fragility}(r) := \mathbb{E} \left[\sum_{b \in r} \sigma(H, b) \right]$$

Heuristic: sequential approach

① Crew Scheduling

Input: Trains on a typical week

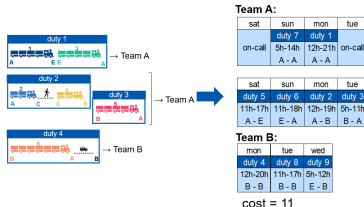
Output: Covering of trains by daily duties with minimum cost, each duty assigned to a team



② Crew Rostering

Input: Duties, each assigned to a team

Output: Covering of trains by blocks with minimum cost, each block assigned to a team (then placed in a roster)



→ Leads to **sub-optimal** solutions

→ Hard to account optimally for **uncertainties**

Model

$$\begin{aligned} & \text{minimize} && \sum_{i \in I} \sum_{b \in B_i} c_b x_{b,i} \\ & \text{s.t.} && \sum_{i \in I} \sum_{b \in B_i: t \in b} x_{b,i} \geq 1 && \forall t \in T \\ & && \sum_{i \in I} \sum_{b \in B_i} \mathbb{E}[\sigma(H, b)] x_{b,i} \leq S \\ & && x_{b,i} \in \{0, 1\} && \forall i \in I, \forall b \in B_i \end{aligned}$$

B_i = set of feasible “blocks” for the team i

→ combinatorial explosion

National input:

1800 trains → $\sim 10^{25}$ blocks

Column Generation: standard resolution methodology of a **linear program** when the number of variables is large

Column Generation

$$\begin{aligned} &\text{minimize} && \sum_{i \in I} \sum_{b \in \bar{B}_i} c_b x_{b,i} \\ &\text{s.t.} && \sum_{i \in I} \sum_{b \in \bar{B}_i: t \in b} x_{b,i} \geq 1 \quad \forall t \in T \\ &&& \sum_{i \in I} \sum_{b \in \bar{B}_i} \mathbb{E}[\sigma(H, b)] x_{b,i} \leq S \\ &&& x_{b,i} \in \{0, 1\} \quad \forall i \in I, \forall b \in \bar{B}_i \subset B_i \end{aligned}$$

Solving the linear relaxation with B_i :

- Iteratively
 - solving the linear relaxation with \bar{B}_i
 - retrieving dual information
 - searching for solutions to a “pricing sub-problem”
 - adding elements to \bar{B}_i
- Optimality guarantee when no elements can be added

Solving the integer problem with B_i :

- Upper bound and feasible solution with $\bar{B}_i \subseteq B_i$

Challenge: Solving the pricing sub-problem **quickly**

For our problem:

Pricing sub-problem = Shortest path with constraints (**Resource Constrained Shortest Path**)

Resource Constrained Shortest Path: setting

Input: Graph with vertices o and d , feasible $o - d$ paths \mathcal{P}_{od} and a (non-linear) cost function c

Output: Feasible $o - d$ path $P \in \mathcal{P}_{od}$ with minimum cost $c(P)$

Resources: Vector tracking accumulated valuable quantities along a path through an extension (non-linear) function

e.g.: shortest $o - d$ path under time budget

→ **resources:** *accumulated length, accumulated arc time*

e.g.: shortest $o - d$ path under stochastic time budget

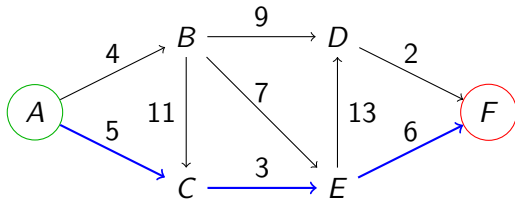
→ **resources:** *accumulated length, accumulated arc time distribution*

Shortest path

Usual shortest path

Input: Graph with vertices o and d , non-negative cost on each arc

Output: $o - d$ path with minimum cost



→ Dijkstra's algorithm

→ A^* search algorithm

Shortest path

A^* search algorithm

Principle: Enumeration algorithm with bounds to discard paths

- Bound b_v under-estimating cost of shortest path from any vertex v to d
- Discard paths P from o to v with “estimated cost” $c(P) + b_v$ greater than one of an explored $o - d$ path

→ with $b_v = 0$: Dijkstra's algorithm

e.g.: shortest route on a map

→ $b_v = \text{distance as the crow flies}$



Resource Constrained Shortest Path: algorithms

Resolution: Enumeration algorithm using

- Key: order of paths processing
- Bound: under-estimate of the resources and cost to reach d
- [not in A^*] Dominance: comparison of resources for paths with same cost

Different algorithms:¹

- Generalized A^*
Key = “estimated cost”, discard paths using “estimated cost”
- Label dominance
Key = cost of path, discard paths using dominance

- Label correcting
Key = “estimated cost”, discard paths using “estimated cost” and dominance

¹synthetized by A.Parmentier in Algorithms for Non-Linear and Stochastic Resource Constrained Shortest Paths, 2017.

For our problem

How to handle the **duty and block feasibility** constraints and the **stochastic constraint**?

- One **graph** per team, with **trains** as **vertices** and **arcs** encoding possible **successions** of trains.
- **Resources** keep track of several indicators, as:
 - block indicators (number of days, etc.)
 - duties indicators (range, driving duration, etc.)
 - delay distributions

Results: without train delays

| | Sequential approach | | Our approach | | |
|----------------------|---------------------|---------|------------------|-------------------------------|------------|
| | Objective | Time | Obj. lower bound | Obj. upper bound ² | Total time |
| Instance 280 trains | 228 | 3min | 205.3 | 209 (-8%) | 21h07min |
| Instance 925 trains | 832 | 26min | 711.9 | 730 (-12%) | 23h48min |
| Instance 1810 trains | 1633 | 1h04min | 1395.0 | 1494 (-8%) | 40h16min |

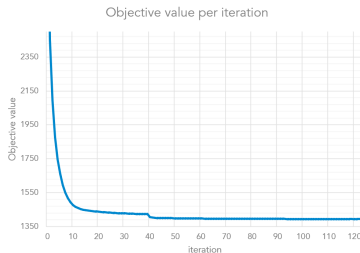
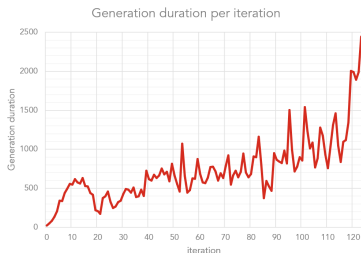


Figure: Column Generation indicators per iteration

²solving MILP with CG output variables and a 1h time limit

Next goals

- Gap closing (or strenghtening) for large instances without train delays
- Getting results with train delays on small and large instances
- Challenging the finite support assumption on the distributions

Thank you!