

# Integrating Crew Scheduling and Crew Rostering for rail freight with train delays

Héloïse Gachet, Frédéric Meunier, Juliette Pouzet

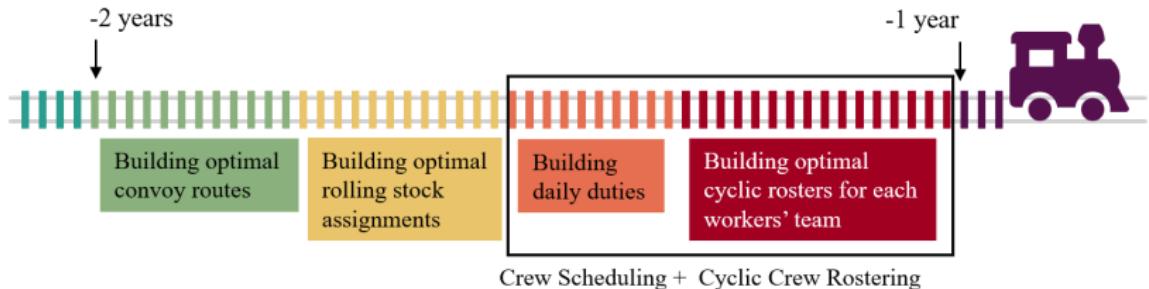
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## Rail freight in France

- Modal share for rail freight: 18% in Europe (10% in France)
- Between 1800 and 2000 trains per week
- Many differences with passengers transportation:
  - Priority goes to passengers
  - Trains mostly at night

# Resource planning



## Contributions

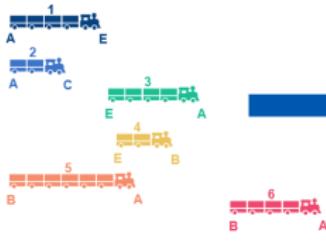
We propose a complete methodology:

- modeling the “resilience” of rosters to train delays at the SNCF
- solving the integrated problem while handling train delays without sampling
- providing a tight lower bound
- leading to an average 8% cost reduction for the deterministic version

# Problem definition

**Input:** Trains on a typical week

**Output:** Covering of trains by “blocks” with minimum cost, each block assigned to a team (each block then placed in a cyclic roster)



Team A:

sun	mon	tue
duty 7	duty 1	
10h-17h	12h-21h	on-call
A - A	A - A	

sat	sun	mon	tue
duty 5	duty 6	duty 2	duty 3
11h-17h	5h-16h	12h-19h	5h-11h
A - E	E - A	A - B	B - A

Team B:

mon	tue	wed
duty 4	duty 8	duty 9
12h-20h	11h-17h	5h-12h
B - B	B - B	E - B

cost = 10

Team A:

mon	tue	wed	thu	fri	sat	sun
duty 1					duty 5	duty 6
12h-21h	on-call		R	R	11h-17h	5h-16h
A - A					A - E	E - A
duty 2	duty 3				duty 7	10h-17h
12h-19h	5h-11h		R	R	R	A - A
A - B	B - A					

Team B:

mon	tue	wed	thu	fri	sat	sun
duty 4	duty 8	duty 9				
12h-20h	11h-17h	5h-12h	R	R	R	R
B - B	B - B	E - B				

## Stochastic train delays: context

Train departure and arrival delays (**primary delays** and **secondary delays**) → disruptions of rosters with propagation within duties.

When delays exceed some threshold, disruptions occur and they induce prohibitive adjustments:

- a full duty, or some of its trains, must be operated by backup drivers;
- an on-call must be added within a block or at its end.

# Stochastic train delays: fragility and assumptions

## Assumptions:

- primary delays are independent variables (not necessarily identically distributed),
- their distributions are known,
- their support is finite.

$H$ : random variable for arrival times (with primary and secondary delays)  
 $\sigma(h, b)$ : number of disruptions in the realization  $H = h$ .

## Roster “fragility” score:

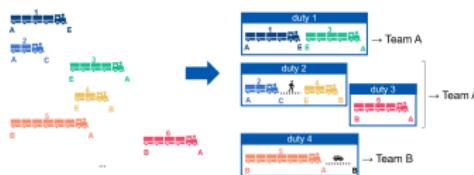
$$\text{fragility}(r) := \mathbb{E} \left[ \sum_{b \in r} \sigma(H, b) \right]$$

# Heuristic: sequential approach

## ① Crew Scheduling

**Input:** Trains on a typical week

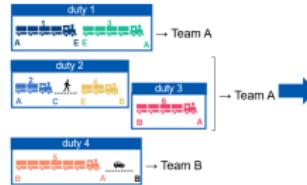
**Output:** Covering of trains by daily duties with minimum cost, each duty assigned to a team



## ② Crew Rostering

**Input:** Duties, each assigned to a team

**Output:** Covering of trains by blocks with minimum cost, each block assigned to a team (then placed in a roster)



Team A:

sat	sun	mon	tue
duty 7	duty 1		on-call
on-call	5h-14h	12h-21h	on-call

Team B:

sat	sun	mon	tue
duty 5	duty 6	duty 2	duty 3
11h-17h	11h-18h	12h-19h	5h-11h

Team B:

mon	tue	wed
duty 4	duty 8	duty 9
12h-20h	11h-17h	5h-12h

cost = 11

- Leads to **sub-optimal** solutions
- Hard to account optimally for **uncertainties**

$$\begin{aligned}
 \text{minimize} \quad & \sum_{i \in I} \sum_{b \in B_i} c_b x_{b,i} \\
 \text{s.t.} \quad & \sum_{i \in I} \sum_{b \in B_i : t \in b} x_{b,i} \geq 1 \quad \forall t \in T \\
 & \sum_{i \in I} \sum_{b \in B_i} \mathbb{E}[\sigma(H, b)] x_{b,i} \leq S \\
 & x_{b,i} \in \{0, 1\} \quad \forall i \in I, \forall b \in B_i
 \end{aligned}$$

$B_i$  = set of feasible “blocks” for the team  $i$

→ combinatorial explosion

National input:

1800 trains →  $\sim 10^{25}$  blocks

Column Generation: standard resolution methodology of a linear program when the number of variables is large

# Column Generation

$$\begin{aligned} \text{minimize} \quad & \sum_{i \in I} \sum_{b \in \bar{B}_i} c_b x_{b,i} \\ \text{s.t.} \quad & \sum_{i \in I} \sum_{b \in \bar{B}_i : t \in b} x_{b,i} \geq 1 \quad \forall t \in T \\ & \sum_{i \in I} \sum_{b \in \bar{B}_i} \mathbb{E}[\sigma(H, b)] x_{b,i} \leq S \\ & x_{b,i} \in \{0, 1\} \quad \forall i \in I, \forall b \in \bar{B}_i \subset B_i \end{aligned}$$

Solving the linear relaxation with  $B_i$ :

- Iteratively
  - solving the linear relaxation with  $\bar{B}_i$
  - retrieving dual information
  - searching for solutions to a “pricing sub-problem”
  - adding elements to  $\bar{B}_i$
- Optimality guarantee when no elements can be added

Solving the integer problem with  $B_i$ :

- Upper bound and feasible solution with  $\bar{B}_i \subseteq B_i$

**Challenge:** Solving the pricing sub-problem **quickly**

**For our problem:**

Pricing sub-problem = Shortest path with constraints (Resource Constrained Shortest Path)

# Resource Constrained Shortest Path: setting

**Input:** Graph with vertices  $o$  and  $d$ , feasible  $o - d$  paths  $\mathcal{P}_{od}$  and a (non-linear) cost function  $c$

**Ouput:** Feasible  $o - d$  path  $P \in \mathcal{P}_{od}$  with minimum cost  $c(P)$

**Resources:** Vector tracking accumulated valuable quantities along a path through an extension (non-linear) function

e.g.: *shortest  $o - d$  path under time budget*

→ **resources**: *accumulated length, accumulated arc time*

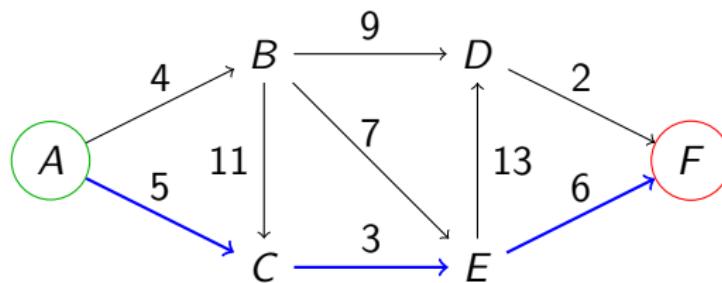
e.g.: *shortest  $o - d$  path under stochastic time budget*

→ **resources**: *accumulated length, accumulated arc time distribution*

## Shortest path

### Usual shortest path

**Input:** Graph with vertices  $o$  and  $d$ , non-negative cost on each arc  
**Output:**  $o - d$  path with minimum cost



→ Dijkstra's algorithm  
→  $A^*$  search algorithm

## Shortest path

### *A\* search algorithm*

**Principle:** Enumeration algorithm with bounds to discard paths

- Bound  $b_v$  under-estimating cost of shortest path from any vertex  $v$  to  $d$
- Discard paths  $P$  from  $o$  to  $v$  with “estimated cost”  $c(P) + b_v$  greater than one of an explored  $o - d$  path

→ with  $b_v = 0$ : Dijkstra's algorithm

e.g.: *shortest route on a map*  
→  $b_v = \text{distance as the crow flies}$



# Resource Constrained Shortest Path: algorithms

**Resolution:** Enumeration algorithm using

- Key: order of paths processing
- Bound: under-estimate of the resources and cost to reach  $d$
- [not in  $A^*$ ] Dominance: comparison of resources for paths with same cost

**Different algorithms:**<sup>1</sup>

- Generalized  $A^*$   
Key = “estimated cost”, discard paths using “estimated cost”
- Label dominance  
Key = cost of path, discard paths using dominance
- Label correcting  
Key = “estimated cost”, discard paths using “estimated cost” and dominance

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<sup>1</sup> synthetized by A.Parmentier in Algorithms for Non-Linear and Stochastic Resource Constrained Shortest Paths, 2017.

## For our problem

How to handle the **duty and block feasibility** constraints and the **stochastic constraint**?

- One **graph** per team, with **trains** as **vertices** and **arcs** encoding possible **successions** of trains.
- **Resources** keep track of several indicators, as:
  - block indicators (number of days, etc.)
  - duties indicators (range, driving duration, etc.)
  - delay distributions

# Results: without train delays

	Sequential approach		Our approach		
	Objective	Time	Obj. lower bound	Obj. upper bound <sup>2</sup>	Total time
Instance 280 trains	228	3min	205.3	<b>209 (-8%)</b>	21h07min
Instance 925 trains	832	26min	711.9	<b>730 (-12%)</b>	23h48min
Instance 1810 trains	1633	1h04min	1395.0	<b>1494 (-8%)</b>	40h16min

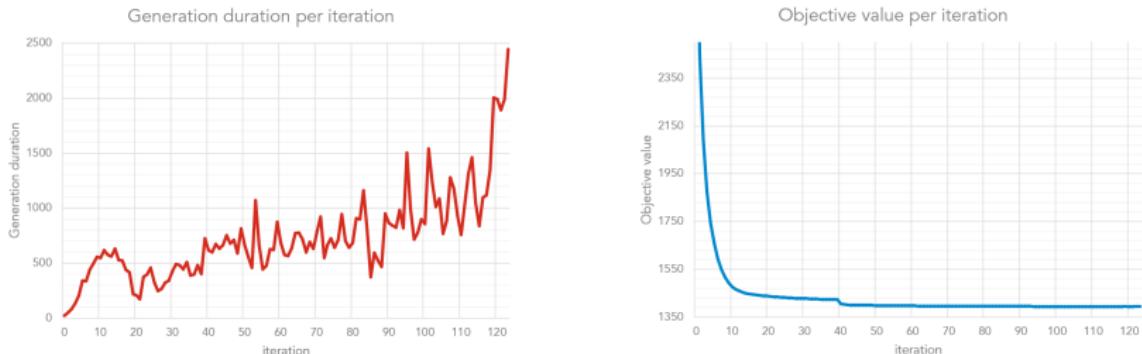


Figure: Column Generation indicators per iteration

<sup>2</sup>solving MILP with CG output variables and a 1h time limit

## Next goals

- Gap closing (or strengthening) for large instances without train delays
- Getting results with train delays on small and large instances
- Challenging the finite support assumption on the distributions

Thank you!